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CLAIMS

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1-32. (canceled)

(currently amended) Signal processing apparatus comprising: 33. a signal amplifier and a frequency converter which operate in succession on an input signal, a pilot signal generator adapted to introduce a pilot signal into the input signal prior to frequency conversion and amplification, and a lineariser which is provided between the amplifier and the frequency converter to introduce a correction signal that is adapted to make the overall input and output characteristic of the apparatus more linear by linearising both the amplifier and frequency converter, wherein: a feedback signal, derived from the output of the apparatus and containing distortion components from the pilot signal produced by at least one of the frequency converter and the amplifier, is used by the lineariser to adapt the correction signal, [[and]] the pilot signal is removed from the output of the apparatus by a filter or by the introduction of a pilot cancellation signal, the lineariser comprises a distortion generator for producing the correction signal from the output signal of whichever of the amplifier and the frequency converter precedes it, and the distortion generator comprises a non-linearity generator arranged to generate a third-

order non-linearity by mixing the input to the non-linearity generator with itself and then with its input

34-35. (canceled)

- (previously presented) A signal processing apparatus according to Claim 33, wherein the 36. pilot signal is one of a CW carrier signal, a full carrier AM signal, a suppressed carrier AM signal, a single sideband signal, a quadrature amplitude modulated signal, a filtered quadrature phase shift keyed signal, a direct sequence spread spectrum signal, and a frequency hopped carrier signal modulated with any of the foregoing kinds of signal.
- 37. (previously presented) Signal processing apparatus according to Claim 33, wherein the pilot signal is one of a two-tone pilot signal and a multi-tone pilot signal.
 - 38. (canceled)

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1	39.	(previously presented) Signal processing apparatus according to Claim 33, wherein the			
2	pilot cancellation	on signal is adjusted using feedback derived from the output of the apparatus.			
1	40.	(previously presented) Signal processing apparatus according to Claim 33, wherein the			
2	pilot cancellati	on signal comprises a frequency converted, phase shifted and amplitude adjusted version			
3	of the pilot sign	nal.			
1	41.	(previously presented) Signal processing apparatus according to Claim 33, wherein a			
2	digital signal p	rocessor is used to control the pilot cancellation signal using feedback from the output of			
3	the signal processing apparatus.				
1	42.	(previously presented) Signal processing apparatus according to Claim 33, further			
∙2	comprising a suppressor for cancelling signals which are images of the pilot signal.				
1	43.	(previously presented) Signal processing apparatus according to Claim 33, wherein a			
2	digital signal p	rocessor is used to control the correction signal using feedback from the output of the			
3	signal processing apparatus.				
1	44-45.	(canceled)			
1	46.	(currently amended) Signal processing apparatus according to Claim [[45]] 33, wherein			
2	the non linearity generator uses at least one of anti-parallel diodes, a FET channel, dual gate GaAsFETs				
3	operating close	e to pinch-off, Shottky diodes, mixers and multipliers in the non-linearity generating			
4	process.				
1	47-48.	(canceled)			
1	49.	(currently amended) Signal processing apparatus according to Claim [[47]] 32, wherein			
2	components of the non-linearity are generated and controlled separately.				
1.	50.	(previously presented) Signal processing apparatus according to Claim 49, wherein			

and are controlled separately.

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in-phase and quadrature signals are produced from each separately generated non-linearity component

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51.	(previously presented) Signal processing apparatus according to Claim 33, wherein the						
frequency converter comprises a mixer for mixing a mixing signal into a received signal destined to be							
frequency conv	verted.						

- (previously presented) Signal processing apparatus according to Claim 33, wherein the 52. frequency converter is an upconverter for converting an intermediate frequency band signal into a radio frequency band signal.
- (previously presented) Signal processing apparatus according to Claim 52, wherein the 53. frequency converter comprises in-phase and quadrature signal paths for handling in-phase and quadrature signals representing a signal at the intermediate frequency band, wherein there is a separate, independently controlled, lineariser operating on each of these signal paths.
- (previously presented) Signal processing apparatus according to Claim 33, wherein the 54. frequency converter is a downconverter for converting a radio frequency band signal into an intermediate frequency band signal.
- (previously presented) Signal processing apparatus according to Claim 54, wherein the frequency converter comprises in-phase and quadrature signal paths for handling in-phase and quadrature signals representing a signal at the intermediate frequency band, wherein there is a separate, 3 4 independently controlled, lineariser operating on each of these signal paths.
 - (previously presented) Signal processing apparatus according to Claim 33, wherein the 56. input signal is a CDMA signal.
 - 57. (currently amended) A method of processing an input signal to produce an output signal, the method comprising the steps of:

signal amplification and frequency conversion,

introducing a pilot signal into the input signal prior to frequency conversion and amplification,

introducing, between the steps of amplification and frequency conversion, a correction signal that is adapted to make the overall input and output characteristic of the signal processing method more linear by linearising both the amplification and frequency conversion,

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8	using a feedback signal, derived from the output signal of the signal processing method and				
9	containing distortion components from the pilot signal produced by at least one of the frequency				
0	conversion and amplification steps, to adapt the correction signal, and				
1	removing the pilot signal from the output signal of the method by filtering or by introducing a				
2	pilot cancellation signal, wherein:				
3	the correction signal is produced by a step of distorting the signal produced by whichev				
4	of the amplifying and frequency conversion steps precedes it, and				
.5	distorting the signal comprises generating a third-order non-linearity by mixing the inpu				
6	signal with itself and then with the input signal.				
1	58-60. (canceled)				
1	61. (previously presented) A method according to Claim 57, comprising the step of				
2	adjusting the pilot cancellation signal using feedback derived from the output signal of the signal				
3	processing method.				
1	62. (canceled)				
1	63. (currently amended) A method according to Claim [[62]] 57, wherein the step of				
2	distortion generation comprises the step of generating and controlling non-linearity components				
3	independently.				
1	64. (previously presented) A method according to Claim 57, wherein the input signal is a				
2	CDMA signal.				
1	65. (currently amended) Signal processing apparatus comprising a signal amplifier and a				
2	frequency converter which operate in succession on an input signal, and a lineariser which is provided				
3	between the amplifier and the frequency converter to introduce a correction signal that is adapted to				
4	make the overall input and output characteristic of the apparatus more linear by linearising both the				
5	amplifier and frequency converter, wherein:				
6	the lineariser comprises a distortion generator for producing the correction signal from the output				
7	signal of whichever of the amplifier and the frequency converter precedes it and				

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8	the distortion generator comprises a non-linearity generator arranged to generate the a third-order						
9	non-linearity by mixing its input signal with itself one or more times to produce the non-linearity the						
10	input to the non-linearity generator with itself and then with its input.						
1	66.	(previously presented) Signal processing apparatus according to Claim 65, wherein the					
2	non linearity g	non linearity generator uses at least one of anti-parallel diodes, a FET channel, dual gate GaAsFETs					
3	operating close	operating close to pinch-off, Shottky diodes, mixers and multipliers in the non-linearity generating					
4	process.						
1	67.	(canceled)					
1	68.	(previously presented) Signal processing apparatus according to Claim 65, wherein					
2	components of	f the non-linearity are generated and controlled separately.					
1	69.	(previously presented) Signal processing apparatus according to Claim 68, wherein					
2	in-phase and q	uadrature signals are produced from each separately generated non-linearity component					
3	and are contro	lled separately.					
1	70.	(currently amended) A method of processing an input signal to produce an output signal					
2	the method co	mprising the steps of signal amplification and frequency conversion, and the step of					
3	introducing , b	etween the steps of amplification and frequency conversion, a correction signal that is					
4	adapted to ma	ke the overall input and output characteristic of the signal processing method more linear					
5	by linearising	both the amplification and frequency conversion, wherein:					
6	the correction signal is introduced between the step of signal amplification and the step of						
7	frequency conversion:						
8	the correction signal is produced by a step of distorting the signal produced by whichever of the						
9	amplifying and frequency conversion steps precedes it, and						
10	the step of distortion generation comprises the step of generating and controlling non-linearity						
11	components independently, and						
12	the step of distortion generation comprises generating a third-order non-linearity by mixing the						
13	input signal w	ith itself and then with the input signal.					
1	71.	(previously presented) Signal processing apparatus according to Claim 33, wherein the					
2	pilot signal is	removed from the output of the apparatus by the filter.					

72		(previously presented) Signal processing apparatus according to Claim 33, wherein	the
pilot signa	l is	emoved from the output of the apparatus by the introduction of the pilot cancellation	
signal.			
73	•	(previously presented) A method according to Claim 57, further comprising the step	p of
removing t	the j	oilot signal from the output signal of the method by filtering.	
74	•	(previously presented) A method according to Claim 57, further comprising the step	p of
removing t signal.	the p	pilot signal from the output signal of the method by introducing the pilot cancellation	
75		(new) Signal processing apparatus comprising:	
as	ign	al amplifier and a frequency converter which operate in succession on an input signal,	
ар	oilot	signal generator adapted to introduce a pilot signal into the input signal prior to frequ	ency
conversion	and	l amplification, and	
a l	inea	riser which is provided between the amplifier and the frequency converter to introduc	e a
correction	sigr	al that is adapted to make the overall input and output characteristic of the apparatus	more
linear by li	inca	rising both the amplifier and frequency converter, wherein:	
	•	a feedback signal, derived from the output of the apparatus and containing distortion	n
componen	ts fr	om the pilot signal produced by at least one of the frequency converter and the amplif	īer, i
used by the	e lin	eariser to adapt the correction signal,	
		the pilot signal is removed from the output of the apparatus by a filter or by the	
introduction	n of	a pilot cancellation signal,	
		the lineariser comprises a distortion generator for producing the correction signal from	om
the output	sign	al of whichever of the amplifier and the frequency converter precedes it,	
		the distortion generator comprises a non-linearity generator arranged to generate the	;
non-lineari	ity b	y mixing its input signal with itself one or more times to produce the non-linearity,	
		components of the non-linearity are generated and controlled separately, and	
		in-phase and quadrature signals are produced from each separately generated	

non-linearity component and are controlled separately.